## Vehicle Accident Analysis and Reconstruction Methods

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| page | Eq/Line            | Correction (should be)   | Comment  |
|------|--------------------|--|--|
| 7    | line 22            | (33, 0.60) should be (32.0, 0.60)  |  |
| 11   | line 23<br>line 25 | $x$ should be $\overline{x}$ $x$ should be $\overline{x}$  |  |
| 12   | lines 1,3,5        | $x$ should be $\overline{X}$   |  |
| 29   | line 33<br>line 35 | $\alpha$ , when $\alpha = \pi/2$ for any $s$ .<br>$\beta = \alpha$ , $F_x = F\cos \alpha$ , $F_y = -F\sin \alpha$  |  |
| 35   | Eq 2.20            | $F_{x}(\alpha,s) = \frac{F_{x}(s)F_{y}(\alpha)s}{\sqrt{s^{2}F_{y}^{2}(\alpha) + F_{x}^{2}(s)\tan^{2}\alpha}} \frac{\sqrt{s^{2}C_{\alpha}^{2} + (1- s )^{2}\cos^{2}\alpha F_{x}^{2}(s)}}{sC_{\alpha}}$                        |  |
| 35   | Eq 2.21            | $F_{y}(\alpha,s) = \frac{F_{x}(s)F_{y}(\alpha)\tan\alpha}{\sqrt{s^{2}F_{y}^{2}(\alpha) + F_{x}^{2}(s)\tan^{2}\alpha}} \frac{\sqrt{(1- s )^{2}\cos^{2}\alpha F_{y}^{2}(\alpha) + \sin^{2}\alpha C_{s}^{2}}}{C_{s}\sin\alpha}$ |  |
| 39   | line 15            | $F_r(\alpha,s) = fF_z \sin \alpha$ should be $F_r(\alpha,s) = fF_z \cos \alpha$  | Typographical error  |
|      | line 16            | $F_x(\alpha,s) = fF_z \cos \alpha$ should be $F_y(\alpha,s) = fF_z \sin \alpha$  | Typographical error  |
| 40   | line 17            | the values in Fig. 2.21 should be  | "the above table" should be replaced by "Fig. 2.21"  |
| 46   | Table 2.1          | Column 5, Sources, should be (top to bottom)   | 2.25, 2.36, 2.13, 2.13, NHTSA FMVSS, blank, USDOT FMCER 2.37, 2.37, 2.37, 2.37, 2.39, 2.40, 2.41 |
| 52   | Eq 3.6a            | $d = -\frac{v_0^2}{2a} = \frac{v_0^2}{2fg}$  | missing minus sign   |
| 53   | line 1             | $\tau = \frac{-11.11}{-7.37} = 1.51  s$  | incorrect denominator  |
| 53   | last line          | The vehicle skids to a stop in 1.51 s  |  |
| 59   | line 3             | $f_r = \frac{F_{tr}}{F_{zr}} = \frac{T/R_w}{F_{zr}} = \frac{1935/0.34}{13947} = 0.408$   | $F_{tr}$ should be torque, $T$ , divided by the rolling radius $R_{w}$                           |

| 59        | line 4   | equal to or higher than about 0.41 will allow   |   |
|-----------|----------|---|---|
| 63        | line 9   | $\sigma_{_{	au}}=\sigma_{_{PDR}}=0.083$   | incorrect decimal point   |
| 63        | line 12  | and a standard deviation of 0.083 s.  | incorrect decimal point   |
| 66        | Eq. 3.44 | $\dot{y} = \dot{\theta}[b + (h_c - R)\theta]$   | current/wrong equation is a repeat of Eq. 3.2                   |
| 66        | Eq. 3.50 | $y(\tau) = c_1(e^{\eta_1 \tau} - 1) + c_2(e^{-\eta_1 \tau} - 1) + c_3(e^{2\eta_1 \tau} - 1) + c_4(e^{-2\eta_1 \tau} - 1)$ | current/wrong equation is a repeat of Eq. 3.3                   |
| 73        | Eq. 4.1  | $(x_i - a)^2 + (y_i - b)^2 = R^2, i = 1, 2, 3$  | current/wrong equation is a repeat of Eq. 4.4                   |
| 150       | Eq. 6.64 | $\Delta V_i = \sqrt{\left(V_{in} - v_{in}\right)^2 + \left(V_{it} - v_{it}\right)^2}$                                     |   |
| 189       | Eg. 7.9  | $W_1 = 2400 \text{ lb } (10.7 \text{ kN}) \text{ and } W_2 = 3350 \text{ lb } (14.9 \text{ kN})$                          | The vehicle weights should be switched in the problem statement |
| 227       | line 3   | Value for $d_0$ of 31.58 should be 46.31  | Statement   |
| 228       | Eq. 9.4  | $K_2 = L[C_1 + 2(C_2 + C_3 + C_4 + C_5) + C_6]/10$  | current/wrong equation is from Example 9.1                      |
| 236       | Eq. 9.15 | $C_{avg} = [C_1 + 2(C_2 + C_3 + C_4 + C_5) + C_6]/10$   | current/wrong equation is a repeat of Eq. 9.12                  |
| 387 - 389 |          | Reference numbers should begin at top of page 387 as 2.21 and continue consecutively through 2.49 on page 389             |   |