

Analysis of the Impact of Articulated Vehicles

INPUT:

Vehicle A {	Body 1:	Tractor A	m_1 :	1,000.00	lb-s ² /ft	I_1 :	3,599.97	ft-lb-s ²	θ_1 :	0.00	deg	v_{1x} :	-72.18	ft/s	v_{3x} :	-72.18	ft/s
	Body 3:	Semitrailer A	m_3 :	1,000.00	lb-s ² /ft	I_3 :	1,000.00	ft-lb-s ²	θ_3 :	0.00	deg	v_{1y} :	0.00	ft/s	v_{3y} :	0.00	ft/s
Vehicle B {	Body 2:	Tractor B	m_2 :	1,300.00	lb-s ² /ft	I_2 :	5,000.01	ft-lb-s ²	θ_2 :	0.00	deg	v_{2x} :	50.00	ft/s	v_{4x} :	50.00	ft/s
	Body 4:	Semitrailer B	m_4 :	1,000.00	lb-s ² /ft	I_4 :	15,000.02	ft-lb-s ²	θ_4 :	0.00	deg	v_{2y} :	0.00	ft/s	v_{4y} :	0.00	ft/s

32.17405
1.466666667

RUN impactAV

Unit Conversion

US

d_1 :	1.00	ft	d_{1R} :	0.00	ft	ϕ_1 :	0.00	deg	ϕ_{1R} :	0.00	deg	ω_1 :	0.0	%/s
d_{3C} :	1.00	ft	d_{3R} :	0.00	ft	ϕ_{3C} :	0.00	deg	ϕ_{3R} :	0.00	deg	ω_3 :	0.0	%/s
d_2 :	1.00	ft	d_{2Q} :	9.91	ft	ϕ_2 :	0.00	deg	ϕ_{2Q} :	0.00	deg	ω_2 :	0.0	%/s
d_{4C} :	1.00	ft	d_{4Q} :	20.01	ft	ϕ_{4C} :	0.00	deg	ϕ_{4Q} :	0.00	deg	ω_4 :	0.0	%/s

If a velocity constraint for rigid body 3 and/or 4 exists, enter the angles (α_3 , α_4). Otherwise, enter "none" (lowercase w/o "").

α_3 :	none	deg
α_4 :	none	deg

If known, enter the external impulse for Vehicles A and B (R and Q, respectively). Otherwise type "unknown" (lowercase w/o "").

R_x :	unknown	lb-s	Γ :	0.00	deg
R_y :	unknown	lb-s	e :	0.00	
Q_x :	unknown	lb-s	μ :	100.00	% μ_0
Q_y :	unknown	lb-s	e' :	-1	$e' = -1$ means that the moment impulse is zero

OUTPUT:

<p>Initial Velocities:</p> <table border="0"> <tr> <td>v_{1x}:</td><td style="background-color: #90EE90;">-72.18</td><td>ft/s</td> <td>v_{1y}:</td><td style="background-color: #90EE90;">0.00</td><td>ft/s</td> <td>ω_1:</td><td style="background-color: #90EE90;">0.00</td><td>%/s</td> <td>v_1:</td><td style="background-color: #90EE90;">72.18</td><td>ft/s</td><td>49.21</td><td>mph</td> </tr> <tr> <td>v_{3x}:</td><td style="background-color: #90EE90;">-72.18</td><td>ft/s</td> <td>v_{3y}:</td><td style="background-color: #90EE90;">0.00</td><td>ft/s</td> <td>ω_3:</td><td style="background-color: #90EE90;">0.00</td><td>%/s</td> <td>v_3:</td><td style="background-color: #90EE90;">72.18</td><td>ft/s</td><td>49.21</td><td>mph</td> </tr> <tr> <td>v_{2x}:</td><td style="background-color: #90EE90;">50.00</td><td>ft/s</td> <td>v_{2y}:</td><td style="background-color: #90EE90;">0.00</td><td>ft/s</td> <td>ω_2:</td><td style="background-color: #90EE90;">0.00</td><td>%/s</td> <td>v_2:</td><td 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<td>R_y:</td><td style="background-color: #90EE90;">0.0</td><td>lb-s</td> <td>R:</td><td style="background-color: #90EE90;">65,351.3</td><td>lb-s</td> <td>ΔV_1:</td><td style="background-color: #90EE90;">65.35</td><td>ft/s</td><td>44.56</td><td>mph</td> </tr> <tr> <td>P_x:</td><td style="background-color: #90EE90;">130,702.6</td><td>lb-s</td> <td>P_y:</td><td style="background-color: #90EE90;">0.0</td><td>lb-s</td> <td>P:</td><td style="background-color: #90EE90;">130,702.6</td><td>lb-s</td> <td>ΔV_3:</td><td style="background-color: #90EE90;">65.35</td><td>ft/s</td><td>44.56</td><td>mph</td> </tr> <tr> <td>P_N:</td><td style="background-color: #90EE90;">130,702.6</td><td>lb-s</td> <td>P_T:</td><td style="background-color: #90EE90;">0.0</td><td>lb-s</td> <td>M:</td><td style="background-color: #90EE90;">0.0</td><td>ft-lb-s</td> <td>ΔV_2:</td><td style="background-color: #90EE90;">56.83</td><td>ft/s</td><td>38.75</td><td>mph</td> </tr> <tr> <td>Q_x:</td><td style="background-color: 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Energy Values:

Initial energy of Veh A	T_{IA} :	5,209,732.6	ft-lb	μ :	0.000	No Sliding at Separation	$PDOF_1$:	0.0	deg
Final energy of Veh A	T_{FA} :	46,610.6	ft-lb	μ_0 :	0.000		$PDOF_2$:	0.0	deg
Initial energy of Veh B	T_{IB} :	2,875,000.0	ft-lb	e :	0.00				
Final energy of Veh B	T_{FB} :	53,602.2	ft-lb	e' :	-1.00				

Initial System Kinetic Energy:	8,084,732.6	ft-lb
Final System Kinetic Energy:	100,212.9	ft-lb
System Energy Loss:	7,984,519.8	ft-lb
Percent System Energy Loss:	98.8	%

